# Discrete-symmetry vortices as angular Bloch modes

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The most general form for symmetric modes of nonlinear discrete-symmetry systems with nonlinearity depending on the modulus of the field is presented. Vortex solutions are demonstrated to behave as Bloch modes characterized by an angular Bloch momentum associated to a periodic variable, periodicity being fixed by the order of discrete point-symmetry of the system. The concept of angular Bloch momentum is thus introduced to generalize the usual definition of angular momentum to cases where O(2) symmetry no longer holds. The conservation of angular Bloch momentum during propagation is demonstrated.

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### I. INTRODUCTION

Rotational symmetry in the x-y plane, defined by the O(2)-symmetry group, implies the conservation of the z-component of angular momentum in two-dimensional nonlinear systems. If the O(2) continuous symmetry is substituted by a discrete rotational symmetry, the usual approach based on Noether's theorem fails since infinitesimal symmetry transformations are no longer allowed. Conservation of angular momentum is expected to breakdown in its usual form and, consequently, nonlinear dynamics should show special features as compared to the O(2)-symmetric case. Since angular momentum is expected to realize differently in discrete-symmetry systems, it is particularly interesting to compare the different behavior of O(2)-symmetric and discrete-symmetry vortices (for an extensive review on vortex solitons and optical vortices see [1] and references therein).

A general feature of vortex solutions is their characteristic phase dislocation, which is determined by an integer number that will be referred to as vorticity (also known as windingnumber, "topological charge," or spin). In O(2)-symmetric systems, rotationally invariant vortices [i.e., vortex solutions whose amplitude is O(2)-symmetric] are eigenfunctions of the angular momentum operator with eigenvalue (angular momentum) given by vorticity. Oppositely, discretesymmetry vortices have no well-defined angular momentum. Examples of both types of vortices can be found in optics as well as in Bose-Einstein condensate (BEC) systems [1]. Vortex solitons in discrete-symmetry nonlinear systems have been numerically predicted to exist in two-dimensional (2D) arrays of coupled waveguides [2], in 2D periodic dielectric media with homogeneous Kerr nonlinearities [3,4], and in photonic crystal fibers with defects [5]. Optical vortices with O(2) symmetry have been experimentally observed in homogeneous self-defocusing nonlinear Kerr media [6] whereas discrete-symmetry optical vortices have been observed in optically induced square photonic lattices [7,8]. The technique of optical lattice induction for generating 2D periodic square lattice structures in the former papers and reported in [9–12] also provides a suitable scenario for creation of alternative tunable refractive index profiles with different types of non-diffracting beams. This includes the possibility of creating Bessel beams induced lattices [13,14] (they can be generated, for example, with holographic methods [15–17]) in which azimuthally modulated lattices of any desired order of discrete rotational symmetry can be produced by higher-order Bessel beams [18]. In this way, the experimental proposals of dielectric structures possessing discrete rotational symmetry of different orders are opening a wide variety of physical systems in which properties of discrete-symmetry optical vortices can be suitably analyzed.

The influence of discrete symmetry in the features of optical vortices are strongly reflected in their angular properties. The phase of a discrete-symmetry vortex presents, besides the typical linear angular dependence characteristic of O(2)-symmetric vortices, an additional sinusoidal contribution completely fixed by the order of the discrete-symmetry of the system (the so-called group phase) [5]. Besides, these systems exhibit a vorticity cutoff equally determined by the order of the discrete-symmetry, in such a way that no vortices of arbitrary order are permitted [19–21].

The aim of this paper is twofold. On the one hand, I will propose a new approach to the search for vortex solutions of a general nonlinear equation that describes not only the conventional optical and BEC cases but also more general situations. I will prove a general expression for symmetric vortex solutions by showing that they are angular Bloch modes. On the second hand, I will extend the conservation of angular momentum to the discrete-symmetry case by introducing the concept of angular Bloch momentum and by demonstrating its conservation during propagation.

# II. ANGULAR BLOCH MODES

Let us consider the 2D nonlinear eigenvalue equation for a system possessing discrete point-symmetry of the  $C_n$  type (discrete rotations of order n):

$$[L_0 + L_{\rm NL}(|\phi|)]\phi = -\mathcal{E}\phi,\tag{1}$$

where  $L_0$  stands for the field-independent part of the full differential operator (linear part) and  $L_{\rm NL}(|\phi|)$  for the nonlin-

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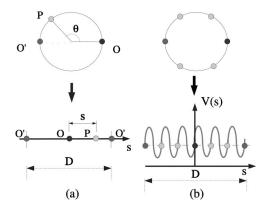


FIG. 1. (a) Mapping of the angular variable  $\theta$  into the noncompact coordinate s. (b) Equivalent periodic potential using this mapping [for an operator of the type  $\tilde{L}(s) = \nabla^2 - V(s)$ ] corresponding to a system with point-symmetry of order n = 6.

ear part. There is no restriction about the specific form of  $L_0$ and  $L_{\rm NI}$ . Usually,  $L_0$  depends on the transverse position coordinates through gradient operators and explicit functions of position [a typical example is  $L_0 = \nabla^2 - V_0(x, y)$ ]. The only assumption made is that the nonlinear part  $L_{\rm NL}$  depends on the field through its modulus exclusively. There can be also an explicit dependence on coordinates through other functions [e.g., inhomogeneous nonlinear coefficients:  $L_{NL}$ =  $\gamma_2(x,y)|\phi|^2 + \gamma_4(x,y)|\phi|^4$ ]. It is considered that the system is invariant under discrete rotations  $C_n$ , so that all operators and coefficients defining  $L_0$  and  $L_{
m NL}$  are assumed to be invariant under discrete rotations of nth order. If one is interested in symmetric solutions, i.e., those functions verifying that their modulus is a  $C_n$ -invariant  $[|\phi(r, \theta+2\pi/n)|]$ = $|\phi(r,\theta)|$ ], then the entire operator  $L=L_0+L_{\rm NL}$  becomes invariant under discrete rotations:  $L(r, \theta) = L(r, \theta + \epsilon)$ ,  $\epsilon$  $\equiv 2\pi/n$ . One can transform this angular dependence into a dependence on a length variable—defined within an interval of the real axis—by using the mapping  $\theta \rightarrow s = \theta D/2\pi$ . This mapping maps the unit circle  $S_1$  (where  $\theta$  is defined:  $\theta$  $\in [-\pi, \pi]$ ) onto the real axis interval [-D/2, D, /2] (see Fig. 1). In terms of the new length variable s, invariance under discrete rotations of the L-operator becomes a periodicity property: if  $\tilde{L}(r,s) \equiv L(r,2\pi s/D)$  then  $\tilde{L}(r,s+a) = \tilde{L}(r,s)$ where a is the period in the noncompact variable s. According to the previous mapping, the period a is fixed by the discrete-rotation angle  $\epsilon$  and thus it depends on the order of the discrete symmetry:  $a = \epsilon D/2\pi = D/n$ . In this way, Eq. (1) for symmetric functions is transformed into  $\tilde{L}(r,s)\varphi(r,s)$  $=-\mathcal{E}\varphi(r,s)$  where  $\varphi(r,s) \equiv \phi(r,2\pi s/D)$ . One has thus converted the original discrete-symmetry eigenvalue problem into a problem of finding the self-consistent modes of a periodic operator. The modulus of these modes are invariant under periodic translations  $[|\varphi(r,s+a)|=|\varphi(r,s)|]$ , a consequence of the invariance of the modulus of a symmetric solution under discrete-rotations. As a clarifying example, one can consider a standard operator of the type  $\tilde{L}(r,s) = \nabla^2$ -V(r,s), where  $V(r,s)=V_0(r,s)+V_{\rm NL}(|\varphi(r,s)|)$ . If  $\varphi(r,s)$  is a solution of  $\tilde{L}\varphi = -\mathcal{E}\varphi$  with periodic modulus then it has to be an eigenmode of the periodic operator generated by itself  $\widetilde{L}(r,s) = \nabla^2 - V(r,s)$ . According to Bloch's theorem, since V is periodic V(r,s+a) = V(r,s) the solution of an eigenvalue equation of the previous type is given by Bloch modes in the periodic variable s. This argument equally applies to the general periodic operator  $\widetilde{L}(r,s)$ , so that the most general solution of  $\widetilde{L}\varphi = -\mathcal{E}\varphi$  is given by 1D Bloch modes [22]:  $\varphi_{pv}(r,s) = e^{ips}u_{pv}(r,s)$ , where p is the Bloch momentum or pseudomomentum of the mode and  $u_p$  is the so-called Bloch function. The index  $\nu$  is known as the band index and occurs because, at a given value of p, there are many different eigenmodes of  $\widetilde{L}$ . Since  $\nu$  does not play a role in the current discussion, I will omit it from the notation (although one has to recall that it is always present). The Bloch function is a periodic function of s with the periodicity of the  $\widetilde{L}$  operator:  $u_p(r,s+a) = u_p(r,s)$ .

One can obtain interesting properties of solutions of Eq. (1) by reinterpreting well-known properties of 1D Bloch modes. A Bloch mode is characterized by the value of its Bloch momentum p. However, unlike plane waves, p is not an eigenvalue of the momentum operator and its value is constrained to lie in a restricted interval, called the Brillouin zone, defined by the condition  $|p| \le \pi/a$ . Moreover, due to the definition of the length coordinate s in terms of the angular variable  $\theta$ , the  $\varphi_p$  function has to be additionally periodic in the interval length D ( $s \in [-D/2, D/2]$ ),  $\varphi_p(r,s) = \varphi_p(r,s+D)$ . As a consequence, a discretization condition for the Bloch momentum p is obtained:  $e^{ipD} = 1 \Rightarrow p = p_m = 2\pi m/D$ ,  $m \in \mathbb{Z}$ . If one reverses the  $\theta \rightarrow s$  mapping by reintroducing the angular variable  $\theta$  in  $\varphi_p(r,s) = e^{ips}u_p(r,s)$ , one obtains the solution in its original form:

$$\phi_m(r,\theta) = e^{im\theta} \widetilde{u}_m(r,\theta), \quad m \in \mathbb{Z}, \quad |m| \le n/2.$$
 (2)

I shall call these solutions angular Bloch modes. They constitute the general symmetric solutions of the nonlinear eigenvalue equation (1). Because of the angular nature of the  $\theta$  variable and its relation to the Bloch momentum  $p_m$  $=2\pi m/D$ , the index m will be referred to as the angular Bloch momentum (or pseudo angular-momentum) of the angular Bloch mode. The restriction on the permitted values of the angular Bloch momentum m is a consequence of the Brillouin zone limitation. The existence of the Brillouin zone for the Bloch momentum p establishes a condition for its permitted values:  $|p| \le \pi/a$ . Since p is discretized according to  $p_m = 2\pi m/D$ ,  $m \in \mathbb{Z}$ , the Brillouin zone limitation effectively imposes a strict constraint into the angular Bloch momentum  $|m| \le D/2a$ . Inasmuch as the period a is determined by the order of symmetry n(a=D/n), one finds that the modulus of the angular Bloch momentum presents the upper bound  $|m| \le n/2$  occurring in Eq. (2).

The expression (2) is the same one that it is obtained for vortex solutions in a nonlinear system with point-symmetry  $C_n$  using group theory arguments [5,19,21]:  $\phi_{\overline{l}}(r,\theta) = e^{i\overline{l}\theta}\phi_0^{(\overline{l})}(r,\theta), \ \overline{l} \in \mathbb{Z}$  being the index of the group representation where the solution belongs to and  $\phi_0^{(\overline{l})}$  a discrete-rotation invariant function,  $\phi_0^{(\overline{l})}(r,\theta+2\pi/n)=\phi_0^{(\overline{l})}(r,\theta)$ . The

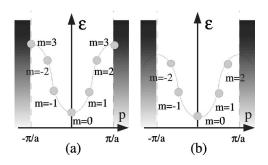


FIG. 2. Schematic representation of Brillouin zones for two different order of symmetries: (a) even n(n=6) and (b) odd n(n=5). Permitted angular Bloch modes are shown.

invariant function  $\phi_0^{(\bar{l})}$  predicted by group theory is nothing but the Bloch function  $\tilde{u}_m$  of the angular Bloch mode (2). Vorticity equals the index of the representation, so that  $\phi_{\bar{l}}$  represents a vortex with vorticity  $v=\bar{l}$  (the exception is the  $\bar{l}=n/2$ —even n—solution) [19]. The comparison of  $\phi_{\bar{l}}(r,\theta)$  =  $e^{i\bar{l}\theta}\phi_0^{(\bar{l})}(r,\theta)$  and Eq. (2) yields to interesting equivalences. Vortex solitons of vorticity  $v=\bar{l}$  appear now as angular Bloch modes carrying angular Bloch momentum  $m=v=\bar{l}$  (m=n/2—even n—excluded). The restriction on angular Bloch momentum  $|m| \le n/2$ , along with the previously established relation between vorticity and angular Bloch momentum, fixes a cutoff for the vorticity:  $|v| \le n/2$  (v=n/2—even v—excluded). This condition can be also rephrased as

$$|v| < n/2$$
 (even n) and  $|v| \le (n-1)/2$  (odd n). (3)

The explicit distinction between even and odd orders is made to remark the different behavior existent in the corresponding Brillouin zones in both cases. For odd n, the discretized Bloch momentum  $p_m$  can never achieve the zone limit  $|p_m| < \pi/a$ , whereas this is certainly possible for even n. This can be clearly visualized in Fig. 2, where two examples of Brillouin zones for even and odd n are shown. It is remarkable that the vorticity cutoff expressed in Eq. (3) has been obtained in a completely different mathematical framework using group-theory arguments [19–21].

# III. CONSERVATION OF ANGULAR BLOCH MOMENTUM AND NONSTATIONARY SOLUTIONS

At this point, it is interesting to compare the discrete-symmetry situation with that corresponding to continuous rotational symmetry. In the O(2) case, Noether's theorem ensures the conservation of the z-component of the angular momentum associated to the  $\phi$  field during propagation:

$$j_z = \int_{\mathbb{R}^2} dx dy \, \phi^*(\mathbf{r}) (\mathbf{r} \wedge \nabla)_z \phi(\mathbf{r}) \Rightarrow \frac{dj_z(z)}{dz} = 0.$$
 (4)

This quantity is also the expectation value of the angular momentum operator  $L_z=-i\partial/\partial\theta$  for the  $\phi$  field, i.e.,  $j_z=\langle\phi|L_z|\phi\rangle$ . Since O(2)-symmetric vortex solutions are of the type  $\phi_{\bar{l}}(r,\theta)=e^{i\bar{l}\theta}f_{\bar{l}}(r)$ , vortex solutions are eigenfunctions of

the angular momentum operator with eigenvalue  $\bar{l}$ . Therefore,  $j_z$  equals  $\bar{l}$  for (normalized to one) vortex solutions and both represent the same constant of motion. On the other hand, the vorticity v of O(2)-symmetric vortices is directly given by  $\bar{l}$ :  $v=j_z=\bar{l}$ . Thus angular-momentum and vorticity are equivalent quantities for O(2)-symmetric vortices.

In a discrete-symmetry system the z-component of angular momentum  $j_z$  [Eq. (4)] is no longer conserved. Noether's theorem does not apply because the symmetry under consideration ceases from being continuous. It is then necessary to find a different conserved quantity that explicitly manifests the discrete-symmetry invariance of the system. It will be proved next that this quantity is nothing but the angular Bloch momentum. In order to carry out the previous demonstration, it is simpler to resort to the representation in terms of the noncompact variable s. It will be assumed that evolution is provided by a first-order operator in the evolution variable z, i.e.,

$$\widetilde{L}\varphi(r,s,z) = -i\frac{\partial\varphi(r,s,z)}{\partial z}.$$
 (5)

This type of evolution operator includes Schrödinger-like equations (like those appearing in nonlinear paraxial evolution in optical systems or in the evolution of Bose-Einstein condensates) but also more general evolution equations, as nonparaxial forward equations in axially invariant optical systems [23].

Up to now the concept of angular Bloch momentum has been closely linked to the concept of angular Bloch modes, i.e., to stationary solutions satisfying Eq. (1). These solutions, besides being characterized by an integer angular Bloch momentum, present a well-defined dependence on the evolution parameter z given by the eigenvalue  $\mathcal{E}$ :  $\phi_m(r,\theta,z)$  $=e^{im\theta}\widetilde{u}_m(r,\theta)e^{-i\mathcal{E}_z}$ . Nevertheless, angular Bloch momentum can be attributed to some specific nonstationary solutions as well. This is so because angular Bloch momentum is related to the transformation properties of the propagating field under discrete rotations of *n*th order ( $C_n$  group) and these transformations can be always defined not only for a stationary field but also for an arbitrary field at a given value of the evolution parameter  $z=z_0$  in the following way:  $\phi(r,\theta,z_0)$  $\xrightarrow{c_n} \phi(r, \theta + 2\pi/n, z_0)$ . If the arbitrary field  $\phi$  at  $z_0$  properly transforms under discrete rotations so that  $\phi_m(r, \theta)$  $+2\pi/n, z_0$  =  $e^{im2\pi/n}\phi_m(r, \theta, z_0), m \in \mathbb{Z}$ , then pseudomomentum can be assigned to it in a straigthforward way, using the same procedure as for stationary solutions, by introducing the "flattening" mapping  $\theta \rightarrow s = \theta D/2\pi$  as before:  $\varphi_m(r, s)$  $+a,z_0$  =  $e^{ip_m a} \varphi_m(r,s,z_0)$  where  $p_m = 2\pi m/D$  is the pseudomomentum [recall that  $\varphi(r,s,z) \equiv \phi(r,\theta,z)$ ]. This property indicates that the nonstationary field  $\phi$  at  $z_0$  is an eigenfunction of the periodic translation operator  $T_a$  since  $T_a \varphi_m(r,s,z_0) = \varphi_m(r,s+a,z_0) = e^{ip_m a} \varphi_m(r,s,z_0)$  thus showing that it owns a well-defined 1D pseudo-momentum  $p_m$  associated to the noncompact variable s. Consequently, the (in principle nonstationary)  $\phi$  field at  $z_0$  can be written in Bloch form as  $\varphi_m(r,s,z_0) = e^{ip_m s} u_m(r,s)_{z_0}$  and, equivalently, it can be restated in terms of the angular variable  $\theta$ —after inverting the  $\theta \rightarrow s$  mapping—as  $\phi_m(r,\theta,z_0) = e^{im\theta}u_m(r,\theta)_{z_0}$ . Therefore, the field  $\phi_m$  at  $z_0$  possesses angular Bloch momentum m using the same criterium established previously for stationary solutions. Certainly, stationary solutions appear as a particular case in which the z dependence of the  $\phi$  field is fixed by the eigenvalue  $\mathcal E$  so that  $u_m(r,\theta,z) = \widetilde u_m(r,\theta)e^{-i\mathcal E z}$ , this expression being valid for all values of z and not only for the fixed one  $z_0$ . These are the angular Bloch modes I have refered to in my previous analyses and for which angular Bloch momentum is trivially conserved.

A different matter is the question of the conservation of angular Bloch momentum for nonstationary solutions. Even though it has been shown that it is possible to have nonstationary solutions with well-defined angular Bloch momentum at a given value of the evolution parameter  $z=z_0$ , it remains an open question whether evolution will preserve angular Bloch momentum for the propagating field when z  $> z_0$ . My aim now is precisely to analyze the evolution of a field amplitude whose initial condition (I will choose it at z =0, for simplicity and without loss of generality) is given by a nonstationary solution with well-defined pseudomomentum  $p_m$ , i.e.,  $\varphi_m(r,s,0) = e^{ip_m s} u_m(r,s)_0$  or, equivalently, with welldefined angular Bloch momentum m, i.e.,  $\phi_m(r, \theta, 0)$  $=e^{im\theta}u_m(r,\theta)_0$ . It is important to stress again that this solution does not need to be a stationary solution of the vortex type behaving as an angular Bloch mode and satisfying the nonlinear eigenvalue Eq. (1). Consequently, this field amplitude can evolve in z in a more complicated manner than that corresponding to a stationary solution. Despite it is a known fact that Bloch momentum is conserved during propagation in a periodic linear system for Bloch modes it is far from obvious in the nonlinear case when dealing with nonstationary solutions. In the latter case, even if the initial field can have well-defined angular Bloch momentum the fact that the evolution operator explicitly depends on the field itself makes the question of conservation of angular Bloch momentum nontrivial.

Let us consider the total evolution from 0 to z as a succession of infinitesimal evolution steps of length  $\varepsilon$  in the limit  $\varepsilon \to 0$ . In a first-order evolution equation of the type given by Eq. (5), the infinitesimal evolution of a field amplitude from the axial slice  $z_j$  to the following slice  $z_{j+1} = z_j + \varepsilon$  is given by

$$\varphi_{j+1}(r,s) = e^{i\tilde{L}(|\varphi_j|)\varepsilon} \varphi_j(r,s). \tag{6}$$

Now I will prove that if  $\varphi_0[\varphi_0 \equiv \varphi(r,s,0)]$  is an (in principle) nonstationary field with well-defined pseudomomentum  $p_m$ , then  $\varphi_j$  is also a field with the same pseudomomentum  $p_m$  for all values of j. The proof is carried out by induction. Let us start by calculating the pseudomomentum of the j=1 amplitude  $\varphi_1$ . The initial amplitude  $\varphi_0$  is a function with well-defined pseudomomentum  $p_m[\varphi_0 = \varphi_{p_m}(r,s)_0 = e^{ip_m s} u_{p_m}(r,s)_0]$  and thus it is an eigenfunction of the translation operator  $T_a \colon T_a \varphi_0(r,s) = \varphi_0(r,s+a) = e^{ip_m a} \varphi_0(r,s)$ . The amplitude  $|\varphi_0|$  is a periodic function of s with periodicity a since it is the modulus of the periodic Bloch function  $u_{p_m}(r,s) : |\varphi_0(r,s+a)| = |\varphi_0(r,s)|$ , so that the nonlineal part of the  $\widetilde{L}$  operator is translational invariant,  $L_{\rm NL}[|\varphi_0(r,s+a)|]$ 

 $=L_{\rm NL}(|\varphi_0(r,s)|)$ . Therefore the full operator  $\widetilde{L}$  is invariant under finite translations since both its linear and nonlinear part are invariant,  $[\widetilde{L}(|\varphi_0|), T_a] = 0$ . This implies in turn that the infinitesimal evolution operator in Eq. (6) commutes with

 $T_a$ :  $\left[e^{i\widetilde{L}(|\varphi_0|)\epsilon}, T_a\right]^{\epsilon \to 0} = \left[1 + i\widetilde{L}(|\varphi_0|)\epsilon, T_a\right] = 0$ . Now I apply the  $T_a$ operator onto  $\varphi_1$  and take into account Eq. (6) for j=0 to find  $T_a \varphi_1 = e^{iL(|\varphi_0|)\varepsilon} T_a \varphi_0 = e^{ip_m a} \varphi_1$ , where I have used the fact that the evolution and translation operator commute between them and that  $\varphi_0$  is an eigenfunction of  $T_a$ . Consequently,  $\varphi_1$ is also a function with well-defined pseudomomentum  $p_m$ . Now, following the induction procedure, I will assume the well-defined pseudomomentum property to be true for  $\varphi_i$  and I will prove it for  $\varphi_{i+1}$ . The demonstration is analogous to the j=0 case. I assume  $\varphi_i$  to be a function with well-defined pseudomomentum  $p_m$ . Then its modulus is translational invariant, so  $\widetilde{L}(|\varphi_i|)$  and  $e^{i\widetilde{L}(|\varphi_j|)\varepsilon}$  are:  $[\widetilde{L}(|\varphi_i|), T_a]$ = $[e^{iL(|\varphi_j|)\varepsilon}, T_a]$ =0. If one acts with the translation operator  $T_a$ onto  $\varphi_{i+1}$ , commutes the translation and evolution operators, and takes into account that  $T_a \varphi_i = e^{ip_m a} \varphi_i$  (well-defined pseudomomentum condition for  $\varphi_j$ ), one readily finds that  $T_a \varphi_{j+1} = e^{ip_m a} \varphi_{j+1}$ . This shows that  $\varphi_j$  is a function with welldefined pseudo-momentum  $p_m$  for all values of j if the initial amplitude  $\varphi_0$  is. Expressed in different words: axial nonlinear evolution preserves the pseudomomentum  $p_m$  and, consequently, the angular Bloch momentum m.

The continuous limit  $\varepsilon \to 0$  of the previous statement permits one to give an expression for the evolving field amplitude  $\varphi(r,s,z)$ : if  $\varphi(r,s,0)=e^{ip_ms}u_{p_m}(r,s)_0$ , then it is also true that  $\varphi(r,s,z)=e^{ip_ms}u_{p_m}(r,s,z)$  for z>0,  $u_{p_m}$  being a z-dependent Bloch function. Note that this function does not need to be of the form corresponding to stationary solutions. If we reintroduce the angular variable  $\theta$  instead of the noncompact one s, one obtains that the general expression for the evolution of an initial field characterized by a well-defined angular Bloch momentum m in the system under consideration is

$$\phi_m(r,\theta,z) = e^{im\theta} \tilde{u}_m(r,\theta,z), \quad m \in \mathbb{Z}, \quad |m| \le n/2.$$
 (7)

This equation establishes that the angular Bloch momentum m is preserved by nonlinear evolution.

It is interesting to remark here the relation between conservation of angular Bloch momentum and stability. It has been well established that weak perturbations (with no welldefined angular Bloch momentum) can induce instabilities on vortices in square lattices [24]. The destruction of the vortex would lead to the nonconservation of the angular Bloch momentum for unstable vortices. Thus conservation of angular Bloch momentum becomes very sensitive to small asymmetric perturbations when one deals with unstable vortices. In the language of group theory, asymmetric perturbations—characterized by not having well-defined angular Bloch momentum or by having angular Bloch momentum different from that of the vortex solution—are equivalent to nondiagonal perturbations, as defined in Refs. [5,20]. They are also responsible for instabilites in vortex and nodal solitons in triangular photonic crystal fibers.

The interplay between ordinary angular momentum and angular Bloch momentum can be visualized by calculating the expectation value of the angular momentum operator for the field amplitude (7). One easily finds that  $j_z(z) = m + \langle \widetilde{u}_m | L_z | \widetilde{u}_m \rangle(z)$  or

$$m = j_z(z) - \langle \widetilde{u}_m | L_z | \widetilde{u}_m \rangle(z). \tag{8}$$

This property shows that angular Bloch momentum is conserved despite angular momentum is not. The expectation value appearing in Eq. (8) is  $j_u^m(z) \equiv \int_{\mathbb{R}^2} \tilde{u}_m^*(-i\partial/\partial\theta) \tilde{u}_m$  corresponding to the angular momentum associated to the  $\theta$ -dependent Bloch functions  $\tilde{u}_m$ . The conservation of the angular Bloch momentum is then the result of a subtle balance between two nonconserved quantities: the conventional angular momentum  $j_z(z)$  and the angular momentum  $j_u^m(z)$  related to Bloch functions. The latter can be attributed to the presence of the discrete-symmetry system that acts as an angular periodic crystal. The dependence of the  $\tilde{u}_m$  Bloch functions on  $\theta$  is a consequence of the angular periodicity of the system. In order to see it, it is clarifying to consider an O(2)-invariant medium as the  $n \rightarrow \infty$  limit of a system with discrete symmetry of *n*th order. In such a case, the  $\tilde{u}_m$  Bloch functions become independent of the  $\theta$  angle and, therefore,

their associated angular momentum vanishes  $j_u^m(z) \to 0$ . As a consequence, angular momentum becomes angular Bloch

momentum  $j_z(z) \to m$  and, therefore, a constant of motion. It is then reasonable to attribute the angular momentum contribution  $j_u^m(z)$  to the discrete-symmetry system acting as an angular periodic crystal. One can interpret Eq. (8) as the statement that during propagation conventional angular momentum is transfered to the discrete-symmetry system (the angular crystal), and vice versa, in such a way angular Bloch momentum is conserved:  $dj_z(z)/dz = -dj_u^m(z)/dz$ .

All the previous arguments apply to every type of evolving field provided it satisfies the initial condition of having well-defined angular Bloch momentum. Conservation of angular Bloch momentum appears then as a property which occurs independently whether the solution is stationary or not. Nonlinear stationary solutions of Eq. (1) are only particular cases to which the general conservation law can be applied to. For discrete-symmetry vortices the angular-momentum-vorticity equivalence  $v = j_z$  of O(2)-invariant solutions is lost. Since discrete-symmetry vortices are angular Bloch modes of vorticity v = m, Eq. (8) establishes a new relation between vorticity and the angular momentum carried by the vortex field [as defined in Eq. (4)]:  $v = j_z - j_u^m$ . In this

way, the angular Bloch momentum concept permits one to unveil the role played by angular momentum and vorticity in systems whose symmetry is no longer O(2) but a point-symmetry of lesser order.

#### IV. CONCLUSIONS

The role played by rotational symmetry is important to classify stationary solutions as well as to determine the dynamics of nonstationary ones. In this paper, I have analyzed the particular consequences that the implementation of rotational symmetry has on these two issues when the system under consideration enjoys a discrete rotational symmetry of finite order. Unlike in systems possessing continuous rotational symmetry, the concept of angular momentum has to be suitably modified in order to incorporate the special features that the discrete nature of rotational symmetry introduce. The key point is the concept of angular Bloch momentum that can be equally applied to both stationary and nonstationary solutions. This concept relies on the transformation properties of stationary and nonstationary fields under discrete rotations, which, when properly managed, can be visualized as translational transformations in a 1D periodic system for the angular variable. The notion of pseudomomentum associated to finite translations in this "angular crystal" appears then naturally, and, in turn, leads to the concept of angular Bloch momentum in a transparent way. When applied to nonlinear stationary solutions, angular Bloch momentum has been shown to be equivalent to the vorticity or topological charge of discrete-symmetry vortices. This remarkable property permits one to reinterpret vortices in systems with discrete rotational symmetry as angular Bloch modes associated to the behavior of the system as an "angular crystal." However, the angular Bloch momentum concept is not exclusive of stationary solutions. It can be also attributed to evolving solutions of nonstationary character. As far as this question is concerned, it has been proven that angular Bloch momentum is conserved by nonlinear evolution described by equations of the type (5).

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